

# NAG C Library Function Document

## nag\_ztrexc (f08qtc)

### 1 Purpose

nag\_ztrexc (f08qtc) reorders the Schur factorization of a complex general matrix.

### 2 Specification

```
void nag_ztrexc (Nag_OrderType order, Nag_ComputeQType compq, Integer n,
                 Complex t[], Integer pdt, Complex q[], Integer pdq, Integer ifst, Integer ilst,
                 NagError *fail)
```

### 3 Description

nag\_ztrexc (f08qtc) reorders the Schur factorization of a complex general matrix  $A = QTQ^H$ , so that the diagonal element of  $T$  with row index **ifst** is moved to row **ilst**.

The reordered Schur form  $\tilde{T}$  is computed by a unitary similarity transformation:  $\tilde{T} = Z^H TZ$ . Optionally the updated matrix  $\tilde{Q}$  of Schur vectors is computed as  $\tilde{Q} = QZ$ , giving  $A = \tilde{Q}\tilde{T}\tilde{Q}^H$ .

### 4 References

Golub G H and Van Loan C F (1996) *Matrix Computations* (3rd Edition) Johns Hopkins University Press, Baltimore

### 5 Parameters

1: **order** – Nag\_OrderType *Input*

*On entry:* the **order** parameter specifies the two-dimensional storage scheme being used, i.e., row-major ordering or column-major ordering. C language defined storage is specified by **order** = Nag\_RowMajor. See Section 2.2.1.4 of the Essential Introduction for a more detailed explanation of the use of this parameter.

*Constraint:* **order** = Nag\_RowMajor or Nag\_ColMajor.

2: **compq** – Nag\_ComputeQType *Input*

*On entry:* indicates whether the matrix  $Q$  of Schur vectors is to be updated, as follows:

if **compq** = Nag\_UpdateSchur, the matrix  $Q$  of Schur vectors is updated;  
if **compq** = Nag\_NotQ, no Schur vectors are updated.

*Constraint:* **compq** = Nag\_UpdateSchur or Nag\_NotQ.

3: **n** – Integer *Input*

*On entry:*  $n$ , the order of the matrix  $T$ .

*Constraint:* **n**  $\geq 0$ .

4: **t[dim]** – Complex *Input/Output*

*Note:* the dimension,  $dim$ , of the array **t** must be at least  $\max(1, \mathbf{pdt} \times \mathbf{n})$ .

If **order** = Nag\_ColMajor, the  $(i, j)$ th element of the matrix  $T$  is stored in **t** $[(j - 1) \times \mathbf{pdt} + i - 1]$  and if **order** = Nag\_RowMajor, the  $(i, j)$ th element of the matrix  $T$  is stored in **t** $[(i - 1) \times \mathbf{pdt} + j - 1]$ .

*On entry:* the  $n$  by  $n$  upper triangular matrix  $T$ , as returned by nag\_zhseqr (f08psc).

*On exit:* **t** is overwritten by the updated matrix  $\tilde{T}$ .

5: **pdt** – Integer *Input*

*On entry:* the stride separating matrix row or column elements (depending on the value of **order**) in the array **t**.

*Constraint:* **pdt**  $\geq \max(1, \mathbf{n})$ .

6: **q[dim]** – Complex *Input/Output*

**Note:** the dimension, *dim*, of the array **q** must be at least  $\max(1, \mathbf{pdq} \times \mathbf{n})$  when **compq** = **Nag\_UpdateSchur**; 1 when **compq** = **Nag\_NotQ**.

If **order** = **Nag\_ColMajor**, the  $(i, j)$ th element of the matrix  $Q$  is stored in **q**[(*j* – 1)  $\times$  **pdq** + *i* – 1] and if **order** = **Nag\_RowMajor**, the  $(i, j)$ th element of the matrix  $Q$  is stored in **q**[(*i* – 1)  $\times$  **pdq** + *j* – 1].

*On entry:* if **compq** = **Nag\_UpdateSchur**, **q** must contain the *n* by *n* unitary matrix  $Q$  of Schur vectors.

*On exit:* if **compq** = **Nag\_UpdateSchur**, **q** contains the updated matrix of Schur vectors.

**q** is not referenced if **compq** = **Nag\_NotQ**.

7: **pdq** – Integer *Input*

*On entry:* the stride separating matrix row or column elements (depending on the value of **order**) in the array **q**.

*Constraints:*

if **compq** = **Nag\_UpdateSchur**, **pdq**  $\geq \max(1, \mathbf{n})$ ;  
if **compq** = **Nag\_NotQ**, **pdq**  $\geq 1$ .

8: **ifst** – Integer *Input*

9: **ilst** – Integer *Input*

*On entry:* **ifst** and **ilst** must specify the reordering of the diagonal elements of  $T$ . The element with row index **ifst** is moved to row **ilst** by a sequence of exchanges between adjacent elements.

*Constraint:*  $1 \leq \mathbf{ifst} \leq \mathbf{n}$  and  $1 \leq \mathbf{ilst} \leq \mathbf{n}$ .

10: **fail** – NagError \* *Output*

The NAG error parameter (see the Essential Introduction).

## 6 Error Indicators and Warnings

### NE\_INT

On entry, **n** =  $\langle \text{value} \rangle$ .

Constraint: **n**  $\geq 0$ .

On entry, **pdt** =  $\langle \text{value} \rangle$ .

Constraint: **pdt**  $> 0$ .

On entry, **pdq** =  $\langle \text{value} \rangle$ .

Constraint: **pdq**  $> 0$ .

### NE\_INT\_2

On entry, **pdt** =  $\langle \text{value} \rangle$ , **n** =  $\langle \text{value} \rangle$ .

Constraint: **pdt**  $\geq \max(1, \mathbf{n})$ .

**NE\_INT\_3**

On entry, **n** = ⟨value⟩, **ifst** = ⟨value⟩, **ilst** = ⟨value⟩.  
 Constraint:  $1 \leq \text{ifst} \leq \text{n}$  and  $1 \leq \text{ilst} \leq \text{n}$ .

**NE\_ENUM\_INT\_2**

On entry, **compq** = ⟨value⟩, **n** = ⟨value⟩, **pdq** = ⟨value⟩.  
 Constraint: if **compq** = Nag\_UpdateSchur, **pdq**  $\geq \max(1, \text{n})$ ;  
 if **compq** = Nag\_NotQ, **pdq**  $\geq 1$ .

**NE\_ALLOC\_FAIL**

Memory allocation failed.

**NE\_BAD\_PARAM**

On entry, parameter ⟨value⟩ had an illegal value.

**NE\_INTERNAL\_ERROR**

An internal error has occurred in this function. Check the function call and any array sizes. If the call is correct then please consult NAG for assistance.

## 7 Accuracy

The computed matrix  $\tilde{T}$  is exactly similar to a matrix  $T + E$ , where

$$\|E\|_2 = O(\epsilon)\|T\|_2,$$

and  $\epsilon$  is the *machine precision*.

The values of the eigenvalues are never changed by the re-ordering.

## 8 Further Comments

The total number of real floating-point operations is approximately  $20nr$  if **compq** = Nag\_NotQ, and  $40nr$  if **compq** = Nag\_UpdateSchur, where  $r = |\text{ifst} - \text{ilst}|$ .

The real analogue of this function is nag\_dtrexc (f08qfc).

## 9 Example

To reorder the Schur factorization of the matrix  $T$  so that element  $t_{11}$  is moved to  $t_{44}$ , where

$$T = \begin{pmatrix} -6.00 - 7.00i & 0.36 - 0.36i & -0.19 + 0.48i & 0.88 - 0.25i \\ 0.00 + 0.00i & -5.00 + 2.00i & -0.03 - 0.72i & -0.23 + 0.13i \\ 0.00 + 0.00i & 0.00 + 0.00i & 8.00 - 1.00i & 0.94 + 0.53i \\ 0.00 + 0.00i & 0.00 + 0.00i & 0.00 + 0.00i & 3.00 - 4.00i \end{pmatrix}.$$

### 9.1 Program Text

```
/* nag_ztrexc (f08qtc) Example Program.
*
* Copyright 2001 Numerical Algorithms Group.
*
* Mark 7, 2001.
*/
#include <stdio.h>
#include <nag.h>
#include <nag_stdlib.h>
#include <nagf08.h>
#include <nagx04.h>
```

```

int main(void)
{
    /* Scalars */
    Integer i, ifst, ilst, j, n, pdq, pdt;
    Integer exit_status=0;
    NagError fail;
    Nag_OrderType order;
    /* Arrays */
    Complex *q=0, *t=0;

#ifdef NAG_COLUMN_MAJOR
#define T(I,J) t[(J-1)*pdt + I - 1]
    order = Nag_ColMajor;
#else
#define T(I,J) t[(I-1)*pdt + J - 1]
    order = Nag_RowMajor;
#endif

    INIT_FAIL(fail);
    Vprintf("f08qtc Example Program Results\n\n");

    /* Skip heading in data file */
    Vscanf("%*[^\n]");
    Vscanf("%ld%*[^\n] ", &n);
#ifdef NAG_COLUMN_MAJOR
    pdq = 1;
    pdt = n;
#else
    pdq = 1;
    pdt = n;
#endif

    /* Allocate memory */
    if ( !(q = NAG_ALLOC(1 * 1, Complex)) ||
        !(t = NAG_ALLOC(n * n, Complex)) )
    {
        Vprintf("Allocation failure\n");
        exit_status = -1;
        goto END;
    }

    /* Read T from data file */
    for (i = 1; i <= n; ++i)
    {
        for (j = 1; j <= n; ++j)
            Vscanf(" ( %lf , %lf )", &t(i,j).re, &t(i,j).im);
    }
    Vscanf("%*[^\n]");
    Vscanf("%ld%ld%*[^\n] ", &ifst, &ilst);

    /* Reorder the Schur factorization T */
    f08qtc(order, Nag_NotQ, n, t, pdt, q, pdq, ifst, ilst, &fail);
    if (fail.code != NE_NOERROR)
    {
        Vprintf("Error from f08qtc.\n%s\n", fail.message);
        exit_status = 1;
        goto END;
    }
    /* Print reordered Schur form */
    x04dbc(order, Nag_GeneralMatrix, Nag_NonUnitDiag, n, n,
            t, pdt, Nag_BracketForm, "%7.4f",
            "Reordered Schur form", Nag_IntegerLabels,
            0, Nag_IntegerLabels, 0, 80, 0, 0, &fail);
    if (fail.code != NE_NOERROR)
    {
        Vprintf("Error from x04dbc.\n%s\n", fail.message);
        exit_status = 1;
        goto END;
    }
END:
    if (q) NAG_FREE(q);
}

```

```

if (t) NAG_FREE(t);

return exit_status;
}

```

## 9.2 Program Data

```

f08qtc Example Program Data
 4 :Value of N
(-6.00,-7.00) ( 0.36,-0.36) (-0.19, 0.48) ( 0.88,-0.25)
( 0.00, 0.00) (-5.00, 2.00) (-0.03,-0.72) (-0.23, 0.13)
( 0.00, 0.00) ( 0.00, 0.00) ( 8.00,-1.00) ( 0.94, 0.53)
( 0.00, 0.00) ( 0.00, 0.00) ( 0.00, 0.00) ( 3.00,-4.00) :End of matrix T
 1 4 :Values of IFST and ILST

```

## 9.3 Program Results

f08qtc Example Program Results

Reordered Schur form				
	1	2	3	4
1	(-5.0000, 2.0000)	(-0.1574, 0.7143)	( 0.1781,-0.1913)	( 0.3950, 0.3861)
2	( 0.0000, 0.0000)	( 8.0000,-1.0000)	( 1.0742, 0.1447)	( 0.2515,-0.3397)
3	( 0.0000, 0.0000)	( 0.0000, 0.0000)	( 3.0000,-4.0000)	( 0.2264, 0.8962)
4	( 0.0000, 0.0000)	( 0.0000, 0.0000)	( 0.0000, 0.0000)	(-6.0000,-7.0000)

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